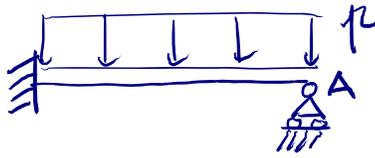


Sdc 15-11-13

esempio precedente



$$M(z) = M_0 + X M_1$$

calcolo di φ_A

sistema equilibrato



$$M_e(z) = -1$$

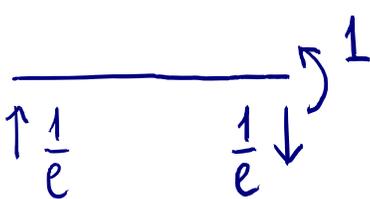
$$L_{Vest} = 1 \cdot \varphi_A = L_{Vint} = \int_0^l M_e \frac{M_0 + X M_1}{r_F} dz = \quad (\gamma = 0)$$

$$= \int_0^l \left(\frac{1}{2r_F} (-z^2 + lz) + \frac{pl^2}{8r_F} \left(-\frac{z}{l} \right) \right) dz = \frac{pl^3}{r_F} \left(\frac{1}{2} \left(-\frac{1}{3} + \frac{1}{2} \right) - \frac{1}{8} \frac{1}{2} \right) =$$

$$= \frac{pl^3}{48r_F}$$

$$\frac{1}{12} - \frac{1}{16} = \frac{4-3}{48} = \frac{1}{48}$$

sistema equilibrato alternativo



$$M_e(z) = -1 + \frac{z}{e}$$

$$\varphi_A = \int_0^l \left(\frac{1}{2r_F} (z^2 - lz) \left(-1 + \frac{z}{e} \right) + \frac{pl^2}{8r_F} \frac{z}{e} \left(-1 + \frac{z}{e} \right) \right) dz =$$

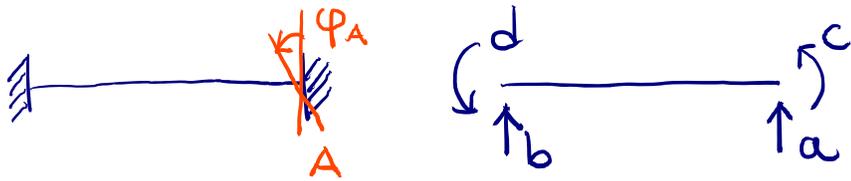
$$= \int_0^l \left(\frac{1}{2r_F} \left(-z^2 + lz + \frac{z^3}{e} - z^2 \right) + \frac{pl^2}{8r_F} \left(-\frac{z}{e} + \frac{z^2}{e} \right) \right) dz =$$

$$= \frac{pl^3}{r_F} \left(\frac{1}{2} \left(-\frac{1}{3} + \frac{1}{2} + \frac{1}{4} - \frac{1}{3} \right) + \frac{1}{8} \left(-\frac{1}{2} + \frac{1}{3} \right) \right) = \frac{pl^3}{48r_F}$$

$$\frac{1}{48} (-8 + 12 + 6 - 8 - 3 + 2) = \frac{1}{48}$$

Esempio: cedimento del vincolo

SdC 15 - 11 - 13

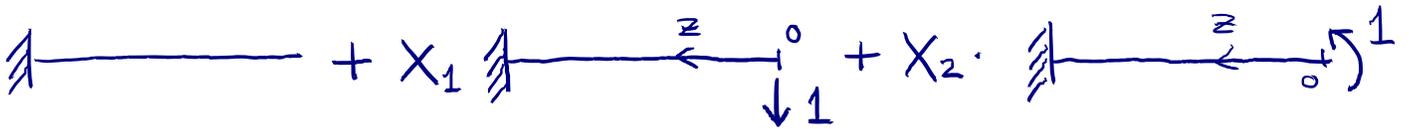


$$a + b = 0$$

$$al + c + d = 0$$

∞^2 soluzioni

scegliendo $X_1 = a$, $X_2 = c$



$$M_0 \equiv 0$$

$$M_1 = z$$

$$M_2 = -1$$

$$\eta_{10} = 0 = \eta_{20}$$

$$\eta_{11} = \int_0^l \frac{M_1^2}{r_F} dz = \frac{l^3}{3r_F}$$

$$\eta_{22} = \int_0^l \frac{M_2^2}{r_F} dz = \frac{l}{r_F}$$

$$\eta_{12} = \int_0^l \frac{M_1 M_2}{r_F} dz = -\frac{l^2}{2r_F} = \eta_{21}$$

$$\eta_1 = 0, \quad \eta_2 = \varphi_A$$

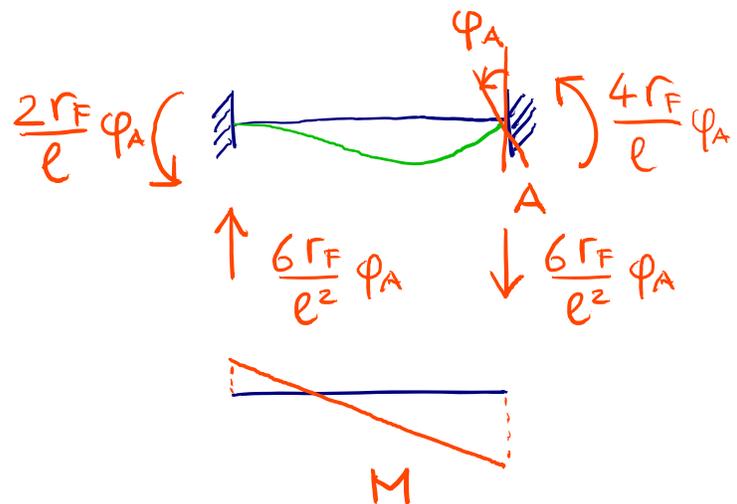
$$\begin{cases} X_1 \eta_{11} + X_2 \eta_{12} = 0 \\ X_1 \eta_{21} + X_2 \eta_{22} = \varphi_A \end{cases}$$

dalla prima equazione

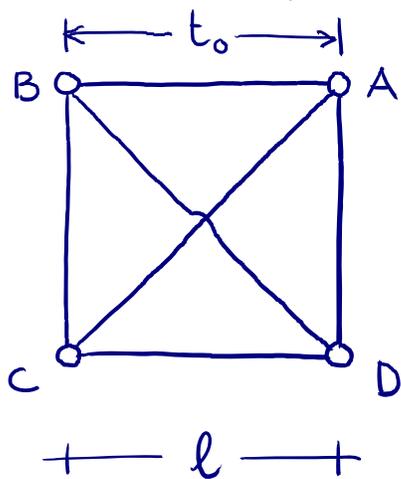
$$X_1 = -X_2 \frac{\eta_{12}}{\eta_{11}} = \frac{3}{2} \frac{X_2}{l}$$

$$X_2 \left(\frac{3}{2} \frac{1}{l} \left(-\frac{l^2}{2r_F} \right) + \frac{l}{r_F} \right) = \varphi_A$$

$$X_2 = \frac{4r_F}{l} \varphi_A, \quad X_1 = \frac{6r_F}{l^2} \varphi_A$$

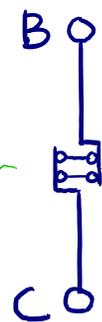
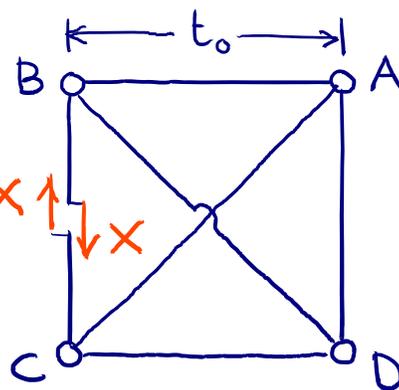


stessa r_E per ogni asta

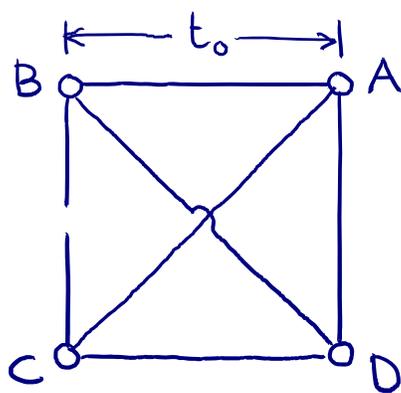


$X = N_{BC}$

η_1 è lo spost. relativo tra le due sezioni



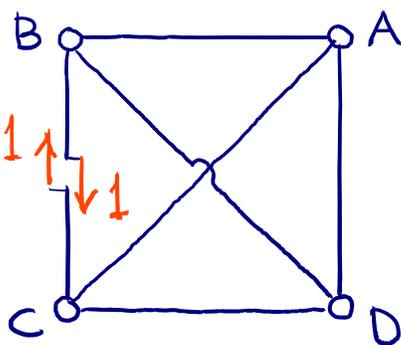
sistema "0"



tutti gli sforzi normali sono nulli (deformazioni termiche, distorsioni e cedimenti non causano sollecitazioni in sistemi staticamente determinati, le equazioni di equilibrio hanno solo la soluzione nulla)

solo $N \neq 0$ taglio e momento sono nulli

sistema "1"



risolvendo le equazioni di equilibrio:

$$N_{AB} = N_{AD} = N_{BC} = N_{CD} = 1$$

$$N_{AC} = N_{BD} = -\sqrt{2}$$

$$\eta_{10} = \sum_{a=1}^N (N_1 \epsilon_0 l)_a = \sum_{a=1}^N \left(N_1 \left(\frac{N_0}{r_E} + \alpha t_0 \right) l \right)_a = 1 \cdot \alpha t_0 l$$

$$\eta_{11} = \sum_{a=1}^N (N_1 \epsilon_0 l)_a = \sum_{a=1}^N \left(\frac{N_1^2}{r_E} l \right)_a = 4 \cdot 1^2 \cdot \frac{l}{r_E} + 2 \cdot (-\sqrt{2})^2 \frac{\sqrt{2} l}{r_E} =$$

$$= 4(1 + \sqrt{2}) \frac{l}{r_E}, \quad \eta_1 = 0 \Rightarrow X = -\frac{\eta_{10}}{\eta_{11}} = -\frac{\alpha t_0 r_E}{4(1 + \sqrt{2})}$$