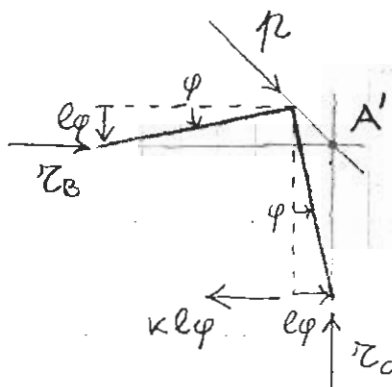
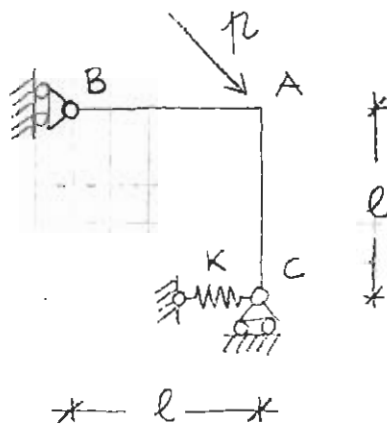




Equilibrio alla traslazione verticale :

$$\tau_C - \frac{P}{\sqrt{2}} = 0 \iff \tau_C = \frac{P}{\sqrt{2}}$$

Equilibrio alla traslazione orizzontale :

$$\frac{P}{\sqrt{2}} + \tau_B - \kappa l \varphi = 0 \iff \tau_B = -\frac{P}{\sqrt{2}} + \kappa l \varphi$$

Equilibrio alla rotazione intorno ad A :

$$\tau_B l \varphi + \tau_C l \varphi - \kappa l^2 \varphi = 0$$

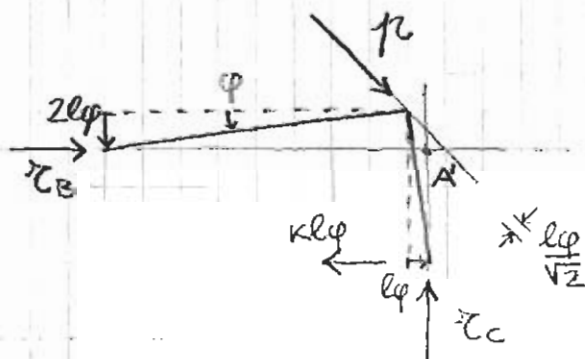
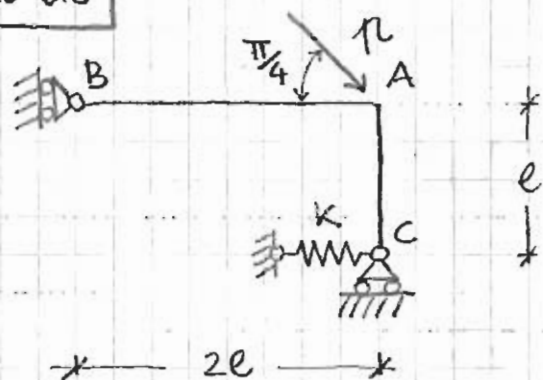
$$\left(-\frac{P}{\sqrt{2}} + \kappa l \varphi + \frac{P}{\sqrt{2}} - \kappa l \right) l \varphi = 0 \iff \kappa l^2 \varphi = 0 \iff \varphi = 0$$

da luogo
ad un φ^2

D'altra parte, scrivendo l'equilibrio alla rotazione intorno ad A' :

$$\kappa l^2 \varphi (1 - \varphi) = 0 \iff \varphi = 0$$

L'equilibrio è possibile solo nella configurazione indeformata.



Come prima $\tau_C = \frac{P}{\sqrt{2}}$ e $\tau_B = -\frac{P}{\sqrt{2}} + k l \phi$

Bilancio dei momenti intorno ad A:

$$\tau_B (2l\phi) + \tau_C l\phi - k l^2 \phi = 0$$

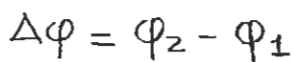
$$-\sqrt{2} P l \phi + 2 k l^2 \phi^2 + \frac{P}{\sqrt{2}} l \phi - k l^2 \phi = 0$$

$$\Leftrightarrow \phi \left(-\frac{1}{\sqrt{2}} P - k l \right) = 0 ; \quad P_C = -\sqrt{2} k l$$

(Il carico che rende la struttura instabile è diretto in verso opposto a quello di figura)

Nella configurazione deformata, il punto A', intersezione delle rette d'azione di τ_B e τ_C , non appartiene alla retta d'azione di P (a differenza del caso precedente). Rispetto ad A', il momento dovuto a P deve essere bilanciato da quello dovuto alla reazione della molla:

$$-P \frac{l\phi}{\sqrt{2}} - k l^2 \phi (1-\phi) = 0 \Leftrightarrow \phi (P + \sqrt{2} k l) = 0$$



$$0 = M_B^{\Pi} = r\ell\varphi_2 - \lambda(\varphi_2 - \varphi_1)$$

$$\begin{bmatrix} \mu l - \lambda & \mu l \\ \lambda & \mu l - \lambda \end{bmatrix} \begin{bmatrix} \varphi_1 \\ \varphi_2 \end{bmatrix} = 0$$

Affinché ci siano soluzioni $(\varphi_1, \varphi_2) \neq (0, 0)$ il determinante della matrice deve essere nullo:

$$(pe - \lambda)^2 - pe\lambda = 0 \iff p^2 - 3\frac{\lambda}{e}p + \frac{\lambda^2}{e^2} = 0$$

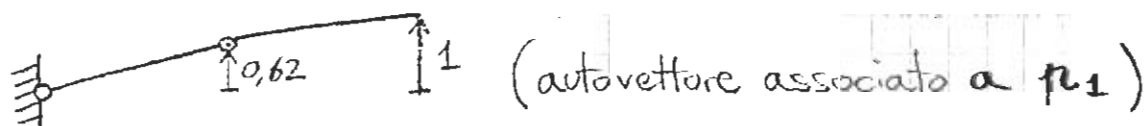
$$r_{1/2} = \frac{1}{2} \left(3 \frac{\lambda}{e} \pm \frac{\lambda}{e} \sqrt{5} \right)$$

$$\mu_1 = \frac{3-\sqrt{5}}{2} \frac{\lambda}{\ell}, \quad \mu_2 = \frac{3+\sqrt{5}}{2} \frac{\lambda}{\ell} \quad ; \quad \mu_c = \mu_1 < \mu_2$$

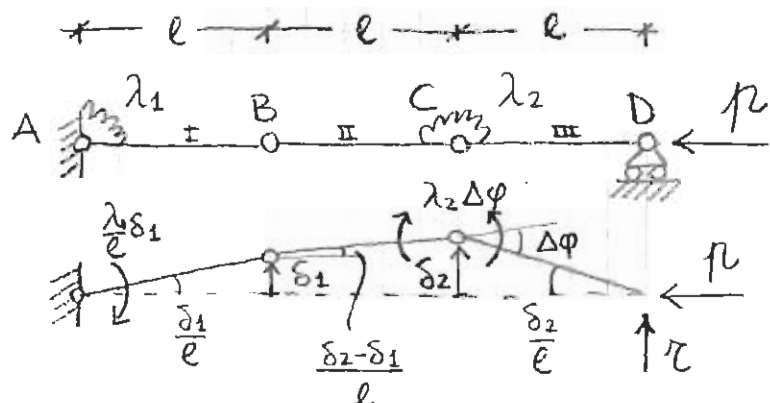
Sostituendo $p = p_1$ nella 1^a equazione:

$$\left(\frac{3-\sqrt{5}}{2} - 1\right) \varphi_1 + \frac{3-\sqrt{5}}{2} \varphi_2 = 0$$

Ponendo $\varphi_2 = \varphi$, si ha $\varphi_1 = -\frac{3-\sqrt{5}}{1-\sqrt{5}} \varphi \simeq 0,62 \varphi$



17



$$\Delta\varphi = \frac{\delta_2}{e} + \frac{\delta_2 - \delta_1}{e} = \frac{2\delta_2 - \delta_1}{e}$$

$$M_A = p(3l) - \frac{\lambda_1}{e}\delta_1 = 0 \Leftrightarrow p = \frac{\lambda_1}{3e^2}\delta_1$$

$$M_B^{\text{III}} = -p\delta_1 + p(2l) = 0 \Leftrightarrow \delta_1 \left(p - \frac{2}{3} \frac{\lambda_1}{e} \right) = 0$$

$$M_C^{\text{III}} = -p\delta_2 + p l + \frac{\lambda_2}{e}(2\delta_2 - \delta_1) = 0$$

$$\Leftrightarrow -p\delta_2 + \frac{\lambda_1}{3e}\delta_1 + \frac{\lambda_2}{e}(2\delta_2 - \delta_1) = 0$$

$$\begin{bmatrix} p - \frac{2}{3} \frac{\lambda_1}{e} & 0 \\ -\frac{\lambda_1}{3e} + \frac{\lambda_2}{e} & p - 2\frac{\lambda_2}{e} \end{bmatrix} \begin{bmatrix} \delta_1 \\ \delta_2 \end{bmatrix} = 0$$

$$\left(p - \frac{2}{3} \frac{\lambda_1}{e} \right) \left(p - 2\frac{\lambda_2}{e} \right) = 0 \quad ; \quad p_1 = \frac{2}{3} \frac{\lambda_1}{e}, \quad p_2 = \frac{2\lambda_2}{e}$$

$$p = p_1, \quad \left(-\frac{\lambda_1}{3e} + \frac{\lambda_2}{e} \right) \delta_1 + 2 \left(\frac{\lambda_1}{3e} - \frac{\lambda_2}{e} \right) \delta_2 = 0 \Leftrightarrow \delta_2 = \frac{\delta_1}{2}$$

$$p = p_2, \quad \delta_1 = 0$$

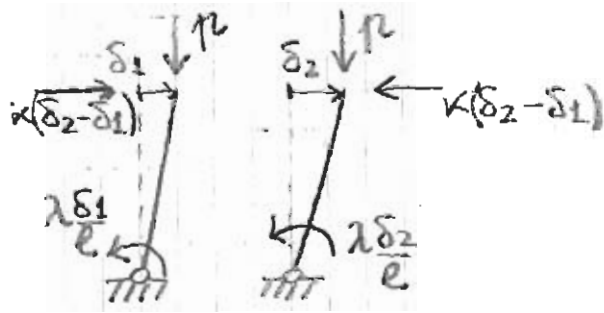
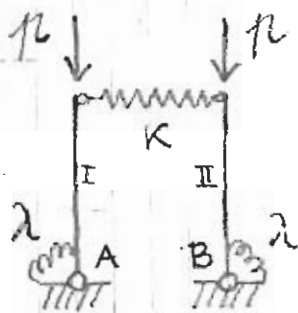


$$p = p_1$$

$$p = p_2$$

$$\frac{2}{3} \frac{\lambda_1}{e} \geq \frac{2\lambda_2}{e} \quad ; \quad \lambda_1 \geq 3\lambda_2$$

Se $\lambda_1 < 3\lambda_2$ allora $p_c = p_1$.



$$M_A^I = \lambda \frac{\delta_1}{l} - P \delta_1 - K(\delta_2 - \delta_1) = 0$$

$$M_B^{II} = \lambda \frac{\delta_2}{l} - P \delta_2 + K l (\delta_2 - \delta_1) = 0$$

Sommando: $(\delta_1 + \delta_2) \left(\frac{\lambda}{l} - P \right) = 0$

Sottraendo: $(\delta_2 - \delta_1) (2Kl - P + \frac{\lambda}{l}) = 0$

$$\left. \begin{aligned} P_1 &= \frac{\lambda}{l}, \quad \delta_2 = \delta_1 \\ P_2 &= \frac{\lambda}{l} + 2Kl, \quad \delta_2 = -\delta_1 \end{aligned} \right\} \Leftrightarrow P_c = P_1$$

20 bis



$$M_B^{II} = \frac{\lambda}{l} \delta_2 + K l (\delta_2 - \delta_1) = 0$$

$$\Leftrightarrow \delta_1 = \left(1 + \frac{\lambda}{Kl^2} \right) \delta_2$$

$$M_A^I = \left[\left(-P + \frac{\lambda}{l} \right) \left(1 + \frac{\lambda}{Kl^2} \right) - Kl \left(-\frac{\lambda}{Kl^2} \right) \right] \delta_2 = 0$$

$$-P_c \left(1 + \frac{\lambda}{Kl^2} \right) + \frac{2\lambda}{l} + \frac{\lambda^2}{Kl^3} = 0$$

$$P_c = \frac{2 + \frac{\lambda}{Kl^2}}{1 + \frac{\lambda}{Kl^2}} \frac{\lambda}{l} = \frac{\lambda}{l} \left(\frac{1}{1 + \frac{\lambda}{Kl^2}} + 1 \right)$$

$$K \rightarrow 0, \quad P_c \rightarrow \frac{\lambda}{l}; \quad K \rightarrow +\infty, \quad P_c \rightarrow 2 \frac{\lambda}{l}$$